

Addressing Modes, Subprograms and Stack Frames

Including Recursion

16-bit Addressing Modes

- 16-bit x86 provides the following addressing modes:

Name	Format	Segment	Example
Direct	[Disp] or Variable	DS	MOV AX, [081H]
			MOV AX, count
Indexed	[DI]	DS	MOV AX, [DI]
	[SI]	DS	MOV AX, [SI]
Based	[BX]	DS	MOV AX, [BX]
	[BP]	SS	MOV AX, [BP]
Indexed-	[DI+disp]	DS	MOV AX, [DI+4]
Displaced	[SI+disp]	DS	MOV AX, [SI+4]
	[BX+disp]	DS	MOV AX, [BX+4]
	[BP+disp]	SS	MOV AX, [BP-4]

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Name	Format	Segment	Example
Based	[BX+DI]	DS	MOV AX, [BX+DI]
-Indexed	[BX+SI]	DS	MOV AX, [BX+SI]
	[BP+DI]	SS	MOV AX, [BP+DI]
	[BP+SI]	SS	MOV AX, [BP+SI]
Based	[BX+DI+disp]	DS	MOV AX, [BX+DI+4]
-Indexed	[BX+SI+disp]	DS	MOV AX, [BX+SI+4]
-Displaced	[BP+DI+disp]	SS	MOV AX, [BP+DI+4]
	[BP+SI+disp]	SS	MOV AX, [BP+SI+4]
String Operations	[SI]	DS	LODSB
	[DI]	ES	STOSB

- For displacement addressing, displacements can be either:
 - 8-bit signed -128 to +127
 - 16-bit unsigned 0 to 65,535 (or 32 bits for 386+)
- Names of addressing modes are not important and are not standardized
- The term "register-indirect" for any based, indexed or indirect modes
- You do NOT need to memorize or understand 16-bit addressing

32 bit Indirect and SIB Addressing

- Any 32-bit general register (including EAX, ECX, EDX, ESP) can be used as an index or base register
 - e.g. MOV EDX, [EAX]

- "scaled-indexed-based addressing" (SIB) allows any 2 general purpose registers together with a scaling factor to be used to compute an address

```
mov eax, [ebx+4*ecx]
mov [edi+2*esp+100h], cx
mov al, [ebx+edx-2]
```

- Scaling factor must be 1, 2, 4, or 8
- Optional displacement can be used
- Allows easy access to arrays of bytes, words, doublewords, or quadwords with indices rather than offsets
- Determination of default segment can get very complex if ESP and / or EBP involved

Indirect Operands

- When the offset of variable is loaded into a base or index register, the register becomes a POINTER to the variable

```
string DB 'This is a string'
...
mov ebx, string
add ebx, 4
mov al, [ebx] ; now what's in al?
```

- The same character can be loaded into al with:


```
mov ebx, string
mov al, [ebx+4]
```
- Or


```
mov ebx, 4
mov al, [ebx+string]
```
- Or


```
mov al, [string+4]
```

Indirect Operands with Displacement

- A register is added to a displacement to obtain the "effective address"
- Displacement is either a number or label whose offset is known at assembly time

- There are several syntactic notations

```
hits resd 100
...
mov ebx, 28 ; address 8th element at 4*(n-1)
mov edx, hits[ebx]; these all do the same thing
mov edx, [ebx+hits]
mov edx, [hits+ebx]
```

- Note that concatenation of symbols in assembler implies addition
- We can also use the base of the array in the index reg:

```
mov ebx, hits
mov edx, [ebx + 28]
```

Indirect Operands with Displacement

```
mov byte [edi] , 'H'  
mov byte [edi+1], 'o'  
mov byte [edi+2], 'w'  
mov byte [edi+3], 'd'  
mov byte [edi+4], 'y'
```

- The above example constructs a string in memory. It gets a bit tricky doing it a word at a time because of back-words storage:

```
mov dword [edi] , 'dwoH'  
mov byte [edi+4], 'y'
```

16 and 32 bit Indirect Operands

- We will discuss indirect addressing in more detail with array operations
- The 16-bit indirect addressing rules are very complex compared to 32 bit rules
- For 32-bit code just consider

Any general purpose register including esp can be used as an index register

With SIB addressing any 2 registers can be combined to form an effective address because the scaling factor is 1,2,4 or 8

(e.g., `mov al, [eax+esi]`

is the same as `mov al, [eax+1*esi]`

A displacement can be used with a single register or with a SIB expression

```
mov al, [ebx+4]
```

```
mov al, [ebx+4*ecx+12]
```

Why SIB Addressing?

- SIB addressing means that you can use registers to index into arrays with a logical index value

```
anarray resd 1024  
.  
.  
.  
mov ecx, 1024 ; number of elements  
mov edx, anarray ; base address  
sub eax, eax ; zero accumulator  
L1:  
add eax, [edx + ecx * 4]  
loop L1
```

Subroutines: CALL and RET

- HLLs have many words for the same concept:

Subroutine
Procedure
Function
Subprogram

- All involve a transfer of control, normally followed by a return to the point of departure
Often a function is considered to be a procedure that returns a value
Some languages make a syntactic distinction, others do not
In C everything is a function but some functions return values
- At the assembler level there is no syntactic difference
We will treat procedures and functions as the same thing in assembly language; both involve a transfer of program control to a set of instructions with CALL or INT that ends with a RET or IRET.
- When a RET (IRET) is executed control returns to the instruction following the CALL (INT) instruction.
- A value-returning function typically returns a value in a register while a procedure or non-value returning function does not

CALL

- Syntax:

```
CALL dest          CALL FAR dest  
CALL NEAR dest
```

- Semantics:

(NEAR)	(FAR)
1. ESP <- ESP - 4	ESP <- ESP - 6
2. [SS:ESP] <- EIP	[SS:ESP+2] <- CS; [SS:ESP] <- EIP
3. EIP <- dest	CS <- HIGH 16 dest; EIP <- LOW 32 dest

(NEAR)	(FAR)
1. SP <- SP - 2	SP <- SP - 4
2. [SS:SP] <- IP	[SS:SP+2] <- CS; [SS:SP] <- IP
3. IP <- dest	CS <- HIGH dest; IP <- LOW dest

CALL

- Note that a FAR CALL will also stack CS then load CS with the new segment address.

- Flags:

ODITZAPC unchanged

- Operands:

```
label reg mem
```

- Notes:

1. Precise syntax of far call varies with assembler
2. Destination address can be indirect:
`CALL [ebx] CALL FAR [ebx]`
`foo resd 1`
`CALL [foo]`
3. Because flags are unaffected flags can be used as parameters

- Indirect calls allow runtime computation of function addresses
Hardware basis for object-oriented programming (OOP) and polymorphic namespaces

RET (RETurn) and RETF (RETurn Far)

- **Purpose:**

Return from a subroutine, popping IP or CS:IP from the stack. RETF forces a far return. An immediate value as an operand adjusts the stack pointer by that amount after popping the return address.

- **Syntax:**

```
1. RET          2. RETF
3. RET imm     4. RETF imm
```

- **Semantics:**

```
1. IP <- [SS:SP]      eip <- [ss:esp]
   SP <- SP + 2       esp <- esp + 4
2. IP <- [SS:SP]      eip <- [ss:esp]
   CS <- [SS:SP+2]    cs <- [ss:esp+4]
   SP <- SP + 4       esp <- esp + 6
3. IP <- [SS:SP]      eip <- [ss:esp]
   SP <- SP + 2 + imm esp <- esp + 4 + imm
4. IP <- [SS:SP]      eip <- [ss:esp]
   CS <- [SS:SP+2]    cs <- [ss:esp+4]
   SP <- SP + 4 + imm esp <- esp + 6 + imm
```

RET Notes

- Even though data can only be stacked as words or dwords, the stack adjustment operand is specified in bytes. Therefore it must always be EVEN.
- Some assemblers do not allow the RETF mnemonic. Instead, the assembler uses
PROC foo NEAR
Or PROC foo FAR
to determine what kind of RET to assemble

RET imm

- The immediate value is used to "clean parameters off the stack" by adjusting the stack pointer

```
push offset hits ;put two params on the
pushd 128        ;stack
call processData
```

```
...
processData:
  push ebp      ; set up stack frame
  mov ebp, esp ; first param is at ebp+8
  mov ecx, [ebp+8]
  mov esi, [ebp+12]
  ...
  pop ebp      ; restore caller's ebp
  ret 8        ; return
```

Stack Frames and Parameters

- EBP (the base pointer) might be better called the Frame Pointer because that is what is used for -- addressing a stack frame
- The key to re-entrant and recursive programming is passing of parameters on the stack AND the use of the stack to store local variables
- A *stack frame* is a structure used to store and access parameters, return addresses, saved registers and local variables

Stack Frame or Activation Record

	Parameters passed by Caller
	Return Address
Frame Pointer ->	Caller's Frame Pointer
	Local (Automatic) Variables
Stack Pointer ->	Saved Registers and Temporary Storage

Passing Parameters

- Three techniques for passing parameters in assembly language:
 1. use registers;
 2. use global variables;
 3. use the stack
- The Stack method is the most flexible technique
Stack technique is used by high-level languages.
- Register parameters are fastest technique
Many C/C++ compilers allow `__fastcall` to specify register parameters
- But you can get into trouble with recursive or reentrant routines if you use register parameters

Re-entrant Code

- Code that cannot call itself, or cannot be interrupted and called by another process before it is finished running is called non-reentrant code.
- Code that can call itself, or can be interrupted and called by another process before it is done is called reentrant code.
- Re-entrant code is essential to operating systems programming

Passing Parameters on the Stack

- Using the stack for parameter passing generally means that the parameters are stacked with PUSHes and then the procedure is called
- To call a function with two parameters:


```
push dwordvar1
push dwordvar2
call func
```
- So at entry to func the stack looks like this

ESP+8	dwordvar1
ESP+4	dwordvar2
ESP	return address

Accessing Parameters

- We could do this


```
pop edi ; save return address in a register
pop eax ; save dwordvar2
pop ebx ; save dwordvar1
```
- But this method has a host of problems. Alternate Plan B:


```
mov eax,[esp+4] ; load dwordvar2
mov ebx,[esp+8] ; load dwordvar1
```
- But what happens if at some point we **push eax**?
 - All of the stack offsets would change
- This is where the base pointer comes into play.
 - EBP by default is stack (SS) relative just as ESP is
 - The convention is that the callee loads ebp to point at something on the stack
 - The "something" is the caller's saved base pointer

Using the Base Pointer

- Here's our call with two parameters:


```
push dwordvar1
push dwordvar2
call func
```
- Inside func we have


```
push ebp ; save caller's base pointer
mov ebp, esp ; load our frame pointer
```

EBP+12	dwordvar1
EBP+8	dwordvar2
EBP+4	return address
EBP = ESP	saved EBP

Cleaning up the Stack

- Who cleans up the stack after the call and removes the parameters?
- It seems a bit difficult for the callee to clean things up - after all we have to pop eip (return address) before we can adjust the stack pointer
- But in most high-level languages and in most asm programs the stack is cleaned by the callee
 - The exception are C and C++ - the CALLER cleans up the stack
- The instruction RET immmed does a return and removes immmed additional bytes after popping the return offset into eip

Cleaning up the Stack

- Cleanup by the CALLEE


```
push dvar1          foo:
push dvar2          push ebp
call foo            mov ebp, esp
... ; continue      ... ; do some processing
                   pop ebp
                   ret 8
```
- Cleanup by the CALLER


```
push dvar1          foo:
push dvar2          push ebp
call foo            mov ebp, esp
add esp,8           ... ; do some processing
... ; continue      pop ebp
                   ret
```

RET imm

- Note that in the Intel architecture it is more efficient to allow the callee to do the cleanup
ret imm is just as fast as ret
one less instruction to code
- But if functions are allowed to have variable numbers of parameters (e.g., C printf or scanf) then the callee cannot clean up the stack but the value for imm is unknown

Prologue and Epilogue

- The code executed at the beginning of the function is called the prologue and the code executed at end before returning is called the epilogue

- Cleanup by the CALLEE

```
push dvar1          foo:
push dvar2          push ebp
call foo            mov ebp, esp
... ; continue      ... ; do some processing
                   pop ebp
                   ret 8
```

- Cleanup by the CALLER

```
push dvar1          foo:
push dvar2          push ebp
call foo            mov ebp, esp
add esp,8           ... ; do some processing
... ; continue      pop ebp
                   ret
```

Simple Subroutine Example: sub3

- Here's what the program does:

```
F:\um\cos335\paulcarter\ms-asm>sub3
```

```
1) Enter an integer number (0 to quit): 101
2) Enter an integer number (0 to quit): 102
3) Enter an integer number (0 to quit): 103
4) Enter an integer number (0 to quit): 0
The sum is 306
```

sub3:1

```
%include "asm_io.inc"
segment .data
    sum    dd    0
segment .bss
    input  resd 1

; algorithm in C code
; i = 1;
; sum = 0;
; while( get_int(i, &input), input != 0 ) {
;     sum += input;
;     i++;
; }
; print_sum(num);

segment .text
global _asm_main
_asm_main:
    enter 0,0          ; setup routine
    pusha
```

sub3:2

```
mov edx, 1          ; edx is 'i' in pseudo-code
while_loop:
    push edx         ; save i on stack
    push dword input ; push address on input on stack
    call get_int
    add esp, 8       ; remove i and &input from stack
    mov eax, [input]
    cmp eax, 0
    je end_while
    add [sum], eax   ; sum += input
    inc edx
    jmp short while_loop
end_while:
    push dword [sum] ; push value of sum onto stack
    call print_sum
    pop ecx          ; remove [sum] from stack

    popa
    leave
    ret
```

sub3:3

```
; get_int - prompt and read integer
; Parameters (in order pushed on stack)
;   number of input (at [ebp + 12])
;   address of word to store input into (at [ebp + 8])
segment .data
prompt db " Enter an integer (0 to quit): ", 0
segment .text
get_int:
    push ebp
    mov ebp, esp
    mov eax, [ebp + 12]
    call print_int
    mov eax, prompt
    call print_string
    call read_int
    mov ebx, [ebp + 8]
    mov [ebx], eax    ; store input into memory
    pop ebp
    ret
```

sub3:4

```

; print_sum
; Parameter:
; sum to print out (at [ebp+8])
; Note: destroys value of eax
segment .data
    result db "The sum is ", 0

segment .text
print_sum:
    push ebp
    mov ebp, esp
    mov eax, result
    call print_string

    mov eax, [ebp+8]
    call print_int
    call print_nl
    pop ebp
    ret
    
```

Local Variables on the Stack

- After a call, and the usual `push ebp` and `mov ebp, esp` the stack looks like this (with three parameters):

ESP+16	Param 1	EBP+16
ESP+12	Param 2	EBP+12
ESP+8	Param 3	EBP+8
ESP+4	Return eip	EBP+4
ESP	Caller's ebp	EBP

- Space for local variables can be reserved on the stack by `SUB ESP, n` where `n` is the number of bytes needed

Local Variables on the Stack

- After `sub esp, 12` the stack looks like this:

ESP+28	Param 1	EBP+16
ESP+24	Param 2	EBP+12
ESP+20	Param 3	EBP+8
ESP+16	Return eip	EBP+4
ESP+12	Caller's ebp	EBP
ESP+8	Local 1	EBP-4
ESP+4	Local 2	EBP-8
ESP	Local 3	EBP-12

- Using this scheme, local variables on the stack are addressed using negative offsets from `ebp`
- Parameters are addressed using positive offsets from `ebp`
- Note that parameter addresses do NOT change relative to `EBP` but they do change relative to `ESP`

%defines for Stack Parameters

- It is good practice to use `%defines` to address local variables and stack parameters

```

#define PARAM1 dword [ebp+16]
#define PARAM2 dword [ebp+12]
#define PARAM3 dword [ebp+8]
#define LOCAL1 dword [ebp-4]
#define LOCAL2 dword [ebp-8]
#define LOCAL3 dword [ebp-12]
    
```

- This makes code easier to write and read (especially when meaningful variable names are used, unlike the example above)

```

MOV edx, LOCAL1
MOV edx, [ebp-4]
    
```

Example

```

MyProc:                                ; computes n = a^2 - b^2
#define nPtr dword [ebp+16] ; n is a pointer to memory
#define a dword [ebp+12]
#define b dword [ebp+8]
#define tmp dword [ebp-4]
    push ebp
    mov ebp, esp
    sub esp, 4                          ; reserve 1 dword on the stack
    push eax                             ; save modified registers
    push ebx
    mov eax, b                           ; compute b^2
    imul eax
    mov tmp, eax                         ; save temp result on stack
    mov eax, a                           ; compute a^2
    imul eax
    sub eax, tmp                          ; ax = a^2 - b^2
    mov ebx, nPtr                        ; get pointer to n
    mov [ebx], eax                       ; save result in n
    pop ebx                               ; restore modified regs
    pop eax
    mov esp, ebp                         ; clear local storage off stack
    ; could also use sub esp, 4
    pop ebp                              ; restore caller's ebp
    ret 12                               ; clear params from stack before returning
    
```

Reference and Value Parameters

- The previous example had two value parameters `a` and `b` and one reference parameter (`a` pointer)
- In order to access the data pointed to by a reference parameter you must first load the pointer into an index register
- Then access memory via the index register
Some other architectures allow memory-indirect addressing

Returning Values from Functions

- Function return values for simple types are almost universal:

bytes AL
words AX
dwords EAX (or DX:AX in 16 bit code)
qwords EDX:EAX
floats ST(0) [top of x87 register stack]

- Note that the issue is not so much type as size
Both ints and pointers are returned in EAX
- For sizes other than those listed above, functions either
 - (A) return a pointer to a data structure
 - OR
 - (B) return a data structure on the stack.

MyProc as a Value-Returning Function

```
MyProc: ; return a^2 - b^2 in eax
#define a dword [ebp+12]
#define b dword [ebp+8]
#define tmp dword [ebp-4]
push ebp
mov ebp,esp
sub esp,4 ; reserve 1 dword on the stack
push eax ; save modified registers
push ebx
mov eax, b ; compute b^2
imul eax
mov tmp, eax ; save temp result on stack
mov eax, a ; compute a^2
imul eax
sub eax, tmp ; ax = a^2 - b^2
pop ebx ; restore modified regs
mov esp,ebp ; clear local storage off stack
pop ebp ; restore caller's ebp
ret 8 ; clear params from stack
```

The PUSHABug

- Watch out for the PUSHABug in value returning functions:

```
myfunc:
pusha ; save registers
....
mov eax, returnval
popa
ret
```

ENTER and LEAVE

- ENTER and LEAVE are CISC instructions designed to simplify prologue and epilogue code
 - ENTER Syntax
`ENTER imm16, imm8`
 - Where imm16 is the number of bytes to reserve on the stack for locals and imm8 is the lexical nesting level
The imm8 parameter is 0 for languages such as C, C++ or Java that do not have nested function scope and could be non-zero for languages such as Javascript, Ada and Pascal
- ```
;ENTER 0, 0
push esp
mov ebp, esp
;ENTER 12, 0
push esp
mov ebp, esp
sub esp, 12
```

## ENTER and LEAVE

- LEAVE Syntax  
`leave`
- Semantics  
`;LEAVE`  
`mov esp, ebp ; deallocate any locals`  
`pop ebp`
- Although designed for HLL compiler writers, ENTER and LEAVE are rarely used because the ENTER instruction is inefficiently implemented  
ENTER is 11, 15, or  $15 + 2 * \text{imm8}$  clocks

## Recursion

- A recursive function is a function that calls itself
- Why is recursion interesting?
- Recursive function theory is another model of computation  
Anything that can be computed by a Turing machine can be computed by a recursive function
- There are some languages whose primary control structure is recursion  
In general any iterative solution to a problem can also be expressed as a recursive solution
- Recursive programs provide elegant and simple solutions to some apparently complex problems

## Example

- The factorial function is easily expressed in both iterative and recursive forms

```
int factorial(int N) {
 int product = 1;
 for (int j=1; j<=N; j++)
 product *= j;
 return product;
}

int factorial(int N) {
 if (N<=1)
 return 1
 else
 return N * factorial (N-1);
}
```

## Recursive Factorial in Asm

```
segment .text
global _factorial
_factorial:
 push ebp ; set up stack frame
 mov ebp, esp
 mov eax, [ebp+8] ; eax = n
 cmp eax, 1 ; if n <= 1 then
 jbe short L1 ; return 1
 dec eax ; push n-1 on the
 push eax ; stack and
 call _factorial ; so eax = fact(n-1)
 add esp, 4 ; remove parameter n-1
 mul dword [ebp+8] ; edx:eax = eax * [ebp+8]
 jmp short L2
L1:
 mov eax, 1
L2:
 pop ebp
 ret
```

## Optimized to use ESP

- If you can be sure that esp will not change during function execution you can bypass stack frame setup and cleanup

```
global _factorial
segment .text
_factorial:
 mov eax, [esp+4] ; eax = n
 cmp eax, 1 ; if n <= 1 then
 jbe term_cond ; return 1
 dec eax ; push n-1 on the
 push eax ; stack and
 call _factorial ; so eax = fact(n-1)
 add esp, 4 ; remove parameter
 mul dword [esp+4] ; edx:eax = eax * [ebp+8]
term_cond:
 mov eax, 1
L2:
 ret
```

## The 3-5 Function

- Any number  $N \geq 8$  can be expressed in the form  $N = (3*K) + (5*M)$

```
Algorithm to compute M and K
if n = 8 then K <- 1 and M <- 1
elseif n = 9 then K <- 3 and M <- 0
elseif n = 10 then K <- 0 and M <- 2
else
 compute K and M for N-3
 add 1 to K
 return K and M
endif
```

## mult35:1

```
segment .text
mult35:
 ; return K and M for N such that N = (3*K)+(5*M)
 ; we return the tuple (K,M) in eax, ebx
 push ebp ; save caller's ebp
 mov ebp, esp ; and set up our stack frame
 mov eax, [ebp+8]
 cmp eax, 10 ; if N > 10
 ja recursion ; recurse
 sub eax, 8 ; is N = 8?
 jz case8 ; yes, return 1 and 1
 dec eax ; if N = 9 then eax is now 1
 jz case9 ; so return 3 and 0
 mov eax, 0 ; N was 10
 mov ebx, 2 ; so return 0 and 2
 jmp short exit
```

## mult35:2

```
case9:
 mov eax, 3 ; return 3 and 0
 mov ebx, 0
 jmp short exit
case8:
 mov eax, 1 ; return 1 and 1
 mov ebx, 1
 jmp short exit
recursion:
 sub eax, 3 ; n <- n-3
 push eax ; push arg to mult35
 call mult35
 add esp, 4 ; clean parameter
 inc eax ; k was returned in ax, add 1 to it
exit:
 pop ebp ; and return to caller
 ret
```